

# RIEGL LiDAR FOR AIRBORNE TOPO-BATHYMETRY

FAST. PRECISE. EFFICIENT.

**NEW**



40° FOV  
circular scan pattern  
up to 100 kHz  
measurement rate  
>2 Secchi depths  
water penetration

5 MPx digital  
camera, IMU/GNSS,  
RIEGL RiLOC, and  
RIEGL software  
**FULLY INTEGRATED**

5.7 kg / 12.5 lbs  
(with camera &  
IMU/GNSS)



40° FOV  
elliptic scan pattern  
up to 200 kHz  
measurement rate

>2 Secchi depths  
water penetration

24 MPx digital  
camera, IMU/GNSS,  
RIEGL RiLOC, and  
RIEGL software  
**FULLY INTEGRATED**

10.3 kg / 22.7 lbs  
(with camera &  
IMU/GNSS)



40° FOV  
elliptic scan pattern  
up to 200 kHz  
measurement rate

adjustable receiver  
field of view for  
operational flexibility

extra full waveform  
analysis tools

>2 Secchi depths  
water penetration

integrated  
12 MPx/24 MPx  
digital camera  
**OPTIONAL**

9.8 - 10.8 kg  
22- 23.8 lbs  
(depending on  
system configuration)



40° FOV  
elliptic scan pattern  
up to 100 kHz  
measurement rate

enhanced  
performance and  
large operational  
envelope from  
75 m up to  
500 m AWL / AGL  
(About Water Level resp.  
About Ground Level)  
flight altitude

>2.5 Secchi depths  
water penetration

integrated  
12 MPx/24 MPx  
digital camera  
**OPTIONAL**

15 - 18.5 kg  
33 - 40.7 lbs  
(depending on  
system configuration)

**NEW VUX-820-G**

**VQ-840-GE**

**VQ-840-GL**

**VQ-860-G**

ready to use all-in-one package

configurable for highest flexibility

**An attractive portfolio tailored to every task in LiDAR bathymetry:**

coastline mapping, habitat observation and change detection, river and inland waterbody survey,  
detailed underwater infrastructure and object detection, hydro engineering, hydro-archeology, water reservoir monitoring



RIEGL TOPO-BATHYMETRIC SENSORS & SYSTEMS  
[www.riegl.com](http://www.riegl.com)

Copyright RIEGL Laser Measurement Systems GmbH © 2026 – All rights reserved.  
Use of this data sheet other than for personal purposes requires RIEGL's written consent.  
This data sheet is compiled with care. However, errors cannot be fully excluded and alternations might be necessary.



**RIEGL**<sup>®</sup>