

RIEGL VUX-SYS[®]

- **complete, compact & lightweight kinematic LiDAR system**
- **fully integrated RIEGL VUX-1 Series LiDAR sensor**
- **various mounting options for highly flexible installation**
- **prepared for remote control via low-bandwidth data link**
- **fully integrated system versions with application-oriented IMU/GNSS unit**
- **compact control unit with various interfacing options**
- **operates up to 4 digital cameras**

The **RIEGL VUX-SYS** is a completely integrated laser scanning system of low weight and compact size for flexible use in kinematic applications (e.g. UAS/UAV/RPAS, helicopter, gyrocopter and ultra-light aircraft installations).

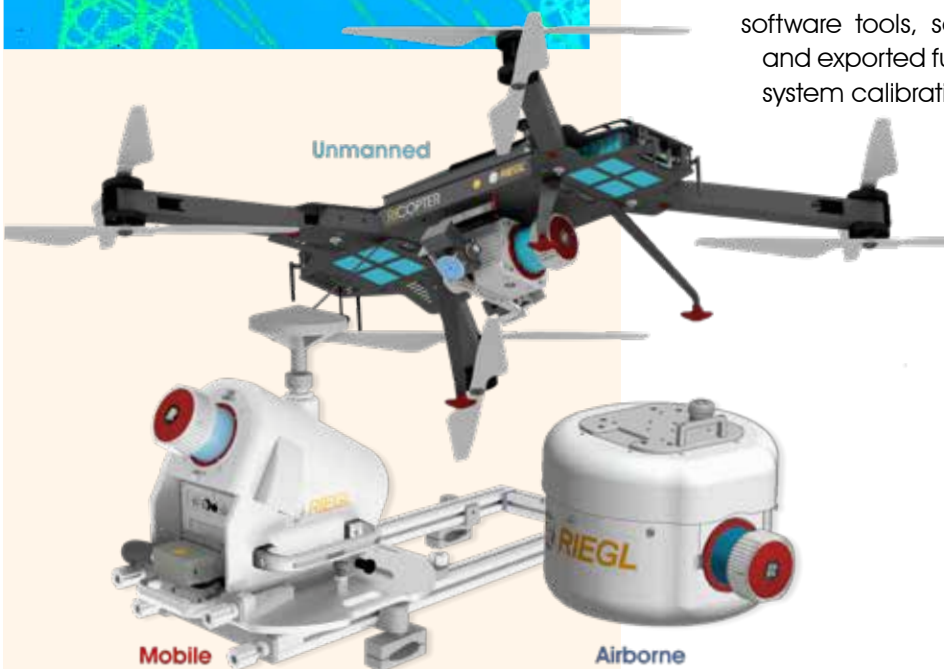
The system comprises a **RIEGL VUX-1 Series LiDAR Sensor**, an IMU/GNSS system and - if applicable - a dedicated control unit. The excellent measurement performance of the VUX-1 in combination with the precise inertial measurement unit and the associated GPS/GLONASS receiver results in survey-grade measurement accuracy over its full range of applications.

The VUX-SYS is specifically designed to be easily installed or exchanged by the user, alternatively either in the **RIEGL VP-1 HeliCopterPod**, the **RiCOPTER** unmanned aerial system, or in any kinematic measuring system, whatsoever.

The VUX-SYS provides interfaces for controlling up to four digital cameras. When installed in the VP-1 HeliCopterPod or the RiCOPTER UAV the VUX-SYS is complemented by up to two cameras.

The small size, low weight, and small number of interconnecting cables required account for a very short set-up time of the system. The VUX-SYS is delivered with the necessary software tools for processing scan data as well as IMU/GNSS data.

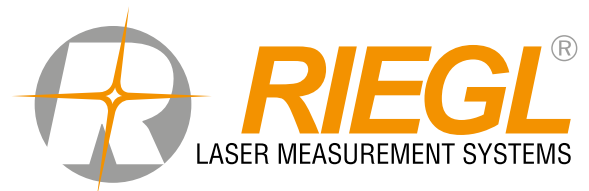
Based on the software bundle **RiPROCESS** and its associated software tools, scan data is geo-referenced, calibrated and exported fully automatically. **RIEGL** offers an optional system calibration service.



Typical applications include

- **Corridor Mapping: Power Line, Railway Track, and Pipeline Inspection**
- **Terrain and Canyon Mapping**
- **Surveying of Urban Environments**
- **Topography in Open-Cast Mining**
- **Agriculture & Forestry**
- **Archeology and Cultural Heritage Documentation**
- **Construction-Site Monitoring**

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www.riegl.com



RIEGL VUX®-SYS - Integration Options

RIEGL VUX-1 with APX-20

interface for 2 optional cameras available

Main Dimensions

VUX-1 with IMU

VUX-1 with IMU and Cooling Fan Device

Weight

VUX-1 with IMU

Cooling Fan Device

Camera(s)

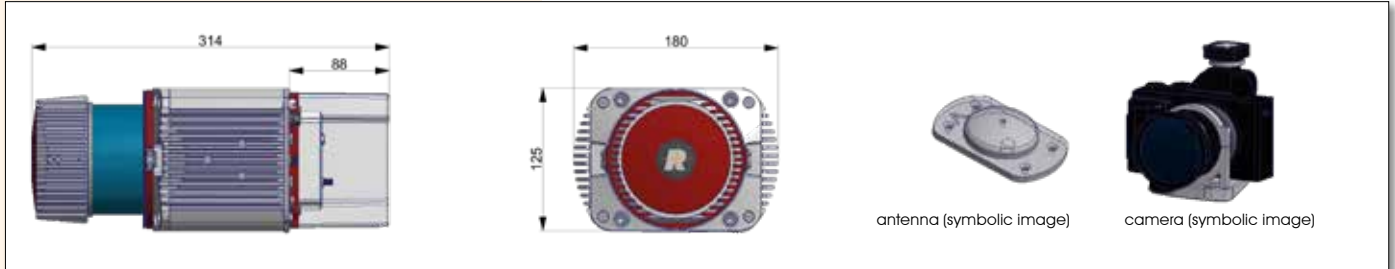
314 x 180 x 125 mm

314 x 209 x 128 mm

approx. 4.2 kg

approx. 0.25 kg

depending on selected camera type



RIEGL VUX-1 with AP20

with separate control unit accommodating the GNSS board stack as well as the camera trigger electronics

for up to 4 optional cameras

Main Dimensions

VUX-1 with IMU

VUX-1 with IMU and Cooling Fan Device

Control Unit

Weight

VUX-1 with IMU

Cooling Fan Device

Control Unit

Camera(s)

296 x 180 x 125 mm

296 x 209 x 128 mm

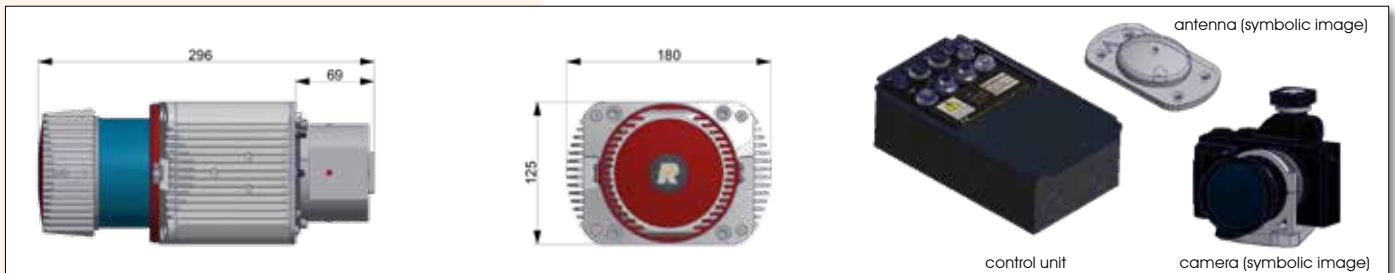
210 x 124 x 79 mm

approx. 4.2 kg

approx. 0.25 kg

approx. 0.9 kg

depending on selected camera type



RIEGL VUX-1 with AP60

with separate control unit accommodating the GNSS board stack as well as the camera trigger electronics

for up to 4 optional cameras

Main Dimensions

VUX-1 with IMU

VUX-1 with IMU and Cooling Fan Device

Control Unit

Weight

VUX-1 with IMU

Cooling Fan Device

Control Unit

Camera(s)

337 x 180 x 125 mm

337 x 209 x 128 mm

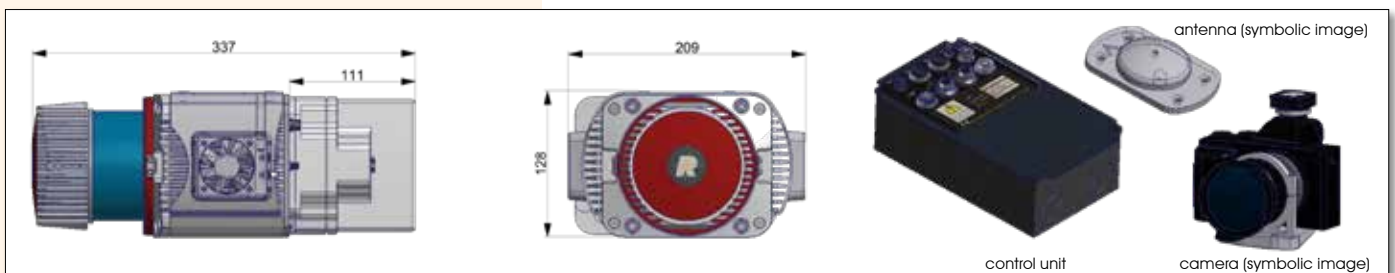
210 x 124 x 79 mm

approx. 6.8 kg

approx. 0.25 kg

approx. 0.9 kg

depending on selected camera type

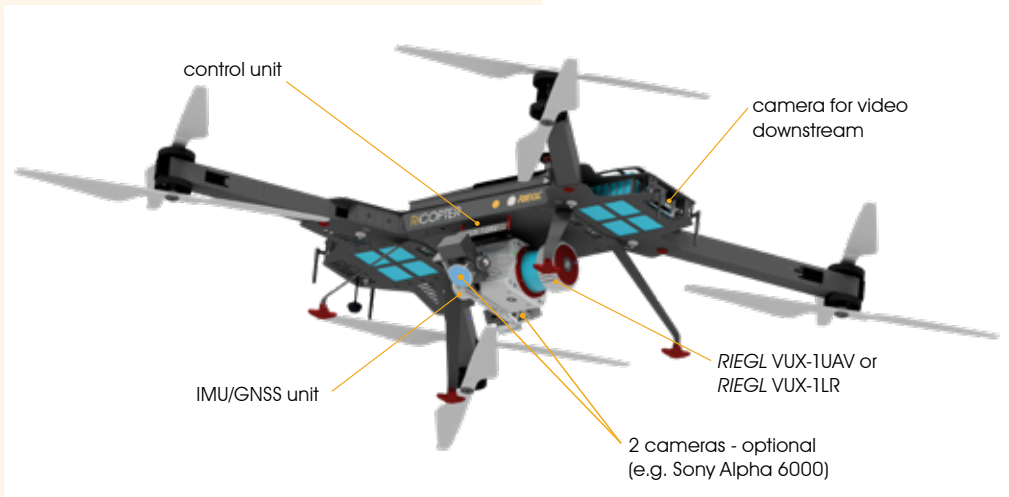


all dimensions in mm

RIEGL VUX®-SYS System Installation

RIEGL VUX®-SYS installed in RiCOPTER (Unmanned)

The VUX-SYS fits the dedicated mounting bay of the RiCOPTER directly without any adaptations. The system is supplemented by two digital cameras, covering a field of view of approximately 160 degrees, whereas the VUX-SYS covers a FOV of 230°. The low weight of the VUX-SYS enables the RiCOPTER to operate up to half an hour at a gross weight of 25 kg.



RIEGL VUX-SYS for RiCOPTER System Components:

- RIEGL VUX-1UAV or RIEGL VUX-1LR LiDAR sensor
- IMU/GNSS unit (Applanix AP20 or APX-20)
- GNSS antenna
- control unit ¹⁾
- camera(s) optional (2x e.g. Sony Alpha 6000)
- connecting cables

RIEGL VUX®-SYS installed in VP-1 (Airborne)

The VUX-SYS fits the small and lightweight RIEGL VP-1 HeliCopterPod, to be mounted on standard hard points and typical camera mounts of manned helicopters. Quick release adapter brackets and a minimum of external cabling (i.e. power supply, LAN, GPS antenna) allow quick system installation and removal.



RIEGL VUX-SYS for VP-1 System Components:

- RIEGL VUX-1UAV or RIEGL VUX-1LR LiDAR sensor
- IMU/GNSS unit (Applanix AP20, APX-20 or AP60)
- GNSS antenna
- control unit ¹⁾
- digital camera(s) (1x Nikon D810, or 1x Phase One iXU, or 2x Sony Alpha 6000)
- connecting cables

RIEGL VUX®-SYS installed in VMQ (Mobile)

Fully integrated into the measuring head of the system, the VUX-SYS is the core part of the RIEGL VMQ Single Scanner Mobile Mapping System. Together with the universal VMQ roof mount the system can be easily mounted on a great variety of vehicles. One single external VMQ main cable minimizes the efforts of the set-up time. The swivel plate allows the operator to achieve different point cloud patterns according to the project requirements.



RIEGL VUX-SYS for VMQ System Components:

- RIEGL VUX-1HA LiDAR sensor (preferred) or RIEGL VUX-1UAV sensor (possible)
- IMU/GNSS unit (Applanix AP20 or AP60)
- GNSS antenna
- control unit ¹⁾
- up to 4 digital camera(s) (e.g., FLIR Ladybug® 5+, Nikon D810, 5 MPix industrial camera)
- connecting cables

¹⁾ for use with AP20 and AP60

Scanner Performance (for details refer to the corresponding RIEGL data sheets)

RIEGL VUX-1 Series Sensor

	VUX-1LR	VUX-1UAV	VUX-1HA ¹⁾
Maximum Range	1,350 m ²⁾	920 m ²⁾	420 m ³⁾
Minimum Range	5 m	3 m	1.2 m
Accuracy / Precision	15 mm / 10 mm	10 mm / 5 mm	5 mm / 3 mm
Laser Pulse Repetition Rate	up to 820 kHz	up to 550 kHz	up to 1000 kHz
Max. Effective Measurement Rate	up to 750,000 meas./sec.	up to 500,000 meas./sec.	up to 1,000,000 meas./sec.
Field of View (selectable) ⁴⁾	up to 330°	up to 330°	up to 360°
Max. Scan Speed	200 scans/sec	200 scans/sec	250 scans/sec

1) Not recommended to be seen as a first choice for ALS and UAV applications because of its lower range capability.

2) Maximum range is specified for natural targets $\rho \geq 60\%$.

3) Maximum range is specified for natural targets $\rho \geq 80\%$.

4) Note limitations when integrated in kinematic systems.

Data Interfaces

Configuration

Scan Data Output

GNSS Interface

Camera

LAN 10/100/1000 Mbit/sec or TTL PWM

LAN 10/100/1000 Mbit/sec or USB 2.0

Serial RS232 interface for data string with GNSS-time information,

TTL input for 1PPS synchronization pulse

4x trigger and event marker

IMU & GNSS

IMU Accuracy

Roll, Pitch ⁶⁾

Heading ⁶⁾

IMU Sampling Rate

Position Accuracy (typ.)

horizontal

vertical

	Applanix AP20 ⁵⁾	Applanix APX-20 ⁵⁾	Applanix AP60 ⁵⁾
Roll, Pitch ⁶⁾	0.015°	0.015°	0.002° ⁷⁾
Heading ⁶⁾	0.035° ⁸⁾	0.035°	0.005° ⁹⁾
IMU Sampling Rate	200 Hz	200 Hz	200 Hz
Position Accuracy (typ.)			
horizontal	< 0.05 m	< 0.05 m	< 0.05 m
vertical	< 0.1 m	< 0.1 m	< 0.1 m

5) See technical details at the according Applanix datasheet

6) values are given for airborne applications

7) roll, pitch for mobile applications: 0.005°

8) heading for mobile applications: 0.05°

9) heading for mobile applications: 0.015°

General Technical Data

Power Supply Input Voltage

Power Consumption

Humidity

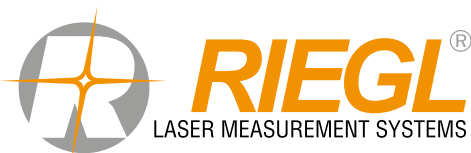
Temperature Range

11 - 34 V DC

typ. 95 W

max. 80 % non condensing @ 31°C

-10°C up to +40°C (operation) / -20°C up to +50°C (storage)



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